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**Affine connections on manifolds
with almost contact 3-structure (**)**

Introduction

An almost contact 3-structure $(\varphi_i, \xi_i, \eta^i)$ ($i = 1, 2, 3$) on a differentiable manifold M , is an aggregate consisting on three almost contact structures, satisfying certain compatibility conditions (v. 1).

In this paper, we shall study affine connections on manifolds with almost contact structures and with almost contact 3-structures.

Among other results, we obtain a necessary and sufficient condition for the existence of a symmetric $(\varphi_i, \xi_i, \eta^i)$ -connection in terms of the tensor fields φ_i , of the 1-forms η^i and of the Nijenhuis tensor fields N_{φ_i} .

1 - Preliminaries

An almost contact structure (φ, ξ, η) [5] on a differentiable manifold is an aggregate consisting on a tensor field φ of type (1, 1), a vector field ξ , and a 1-form η which satisfy

$$\varphi^2 = -I + \eta \otimes \xi \quad \eta(\xi) = 1$$

where \otimes denotes the tensor product, and I is the identity tensor.

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Let us suppose that a differentiable manifold admits three almost contact structures $(\varphi_i, \xi_i, \eta^i)$ ($i = 1, 2, 3$) satisfying

$$\begin{aligned} \eta^i(\xi_j) &= \delta_i^j & \varphi_i(\xi_j) &= -\varphi_j(\xi_i) = \xi_k \\ \eta^i \circ \varphi_j &= -\eta^j \circ \varphi_i = \eta^k & \varphi_i \varphi_j - \eta^j \otimes \xi_i &= -\varphi_j \varphi_i + \eta^i \otimes \xi_j = \varphi_k \end{aligned}$$

for any cyclic permutation (i, j, k) of $(1, 2, 3)$. Then $(\varphi_i, \xi_i, \eta^i)$ ($i = 1, 2, 3$) is called an almost contact 3-structures [1]. The dimension of a manifold with an almost contact 3-structure is $4n + 3$ for some non negative integer n .

Let M be a differentiable manifold with an almost contact 3-structure. Then, the structure group of the tangent bundle is reducible to $Sp(n) \times I_3$, where $Sp(n)$ denotes the real representation of the symplectic group. The converse is also true.

2 - Affine connections on almost contact manifolds

Let M be a differentiable manifold with an almost contact structure (φ, ξ, η) . Two linear operators F_1, F_2 acting on the space of tensor of type $(1, 2)$ are defined as follows.

Def. 2.1. Let P be a tensor field of type $(1, 2)$.
Then

$$\begin{aligned} F_1 P(X, Y) &= \frac{1}{2} \{-\varphi^2 P(X, Y) - \varphi P(X, \varphi Y)\} \\ F_2 P(X, Y) &= \frac{1}{2} \{-\varphi^2 P(X, Y) + \varphi P(X, \varphi Y)\} \end{aligned}$$

for any vector fields X, Y on M .

Proposition 2.1. *The following identities and implications hold*

$$\begin{aligned} (2.1) \quad & F_1 + F_2 = -\varphi^2 \\ (2.2) \quad & F_1 F_1 P(X, Y) = F_1 P(X, Y) - \frac{1}{2} F_1 P(X, \eta(Y)\xi) \\ & F_2 F_2 P(X, Y) = F_2 P(X, Y) - \frac{1}{2} F_2 P(X, \eta(Y)\xi) \end{aligned}$$

$$(2.3) \quad F_1 F_2 P(X, Y) = F_2 F_1 P(X, Y) - \frac{1}{2} F_1 P(X, \eta(Y) \xi)$$

$$(2.4) \quad \text{If } F_1 P(X, Y) = -\frac{1}{2} \varphi^2 P(X, \eta(Y) \xi) \quad \text{then}$$

$$F_2 P(X, Y) = -\varphi^2 P(X, Y) + \frac{1}{2} \varphi^2 P(X, \eta(Y) \xi).$$

$$\text{Similarly, if } F_2 P(X, Y) = -\frac{1}{2} \varphi^2 P(X, \eta(Y) \xi) \quad \text{then}$$

$$F_1 P(X, Y) = -\varphi^2 P(X, Y) + \frac{1}{2} \varphi^2 P(X, \eta(Y) \xi).$$

(2.5) *Given a tensor field P of tupe (1, 2), there exists a tensor field Q of type (1, 2) such that $F_1 Q(X, Y) = -\varphi^2 P(X, Y)$ if and only if*

$$F_2 P(X, Y) = -\frac{1}{2} \varphi^2 P(X, \eta(Y) \xi).$$

Similarly, there exists a tensor field Q such that $F_2 Q(X, Y) = -\varphi^2 P(X, Y)$ if and only if

$$F_1 P(X, Y) = -\frac{1}{2} \varphi^2 P(X, \eta(Y) \xi).$$

Proof. (2.1) and (2.4) follow directly from Def. 2.1; (2.2) and (2.3) are shown by direct computation. Finally, if there exists a tensor field Q such that $F_1 Q(X, Y) = -\varphi^2 P(X, Y)$, then

$$\begin{aligned} & F_2 F_1 Q(X, Y) \\ &= \frac{1}{2} (\varphi^4 P(X, Y) - \varphi^3 P(X, \varphi Y)) = \frac{1}{2} (-\varphi^2 P(X, Y) + \varphi P(X, \varphi Y)) = F_2 P(X, Y). \end{aligned}$$

Then, by (2.3),

$$F_2 F_1 Q(X, Y) = \frac{1}{2} F_1 Q(X, \eta(Y) \xi) = -\frac{1}{2} \varphi^2 P(X, \eta(Y) \xi) = F_2 P(X, Y).$$

Conversely, if

$$F_2 P(X, Y) = -\frac{1}{2} \varphi^2 P(X, \eta(Y) \xi)$$

then, by (2.4),

$$F_1 P(X, Y) = -\varphi^2 P(X, Y) + \frac{1}{2} \varphi^2 P(X, \eta(Y) \xi)$$

and hence

$$F_1(P(X, Y) + P(X, \eta(Y)\xi)) = -\varphi^2 P(X, Y).$$

Now, it suffices to take

$$Q(X, Y) = P(X, Y) + P(X, \eta(Y)\xi).$$

Theorem 2.1. *On a differentiable manifold M with an almost contact structure (φ, ξ, η) , there always exists an affine connection such that φ, ξ and η , are all covariantly constant with respect to it.*

Proof. Let us consider an arbitrary affine connection $\overset{\circ}{\nabla}$ on M . Then, define the connection ∇' by

$$\nabla'_X Y = \overset{\circ}{\nabla}_X Y - \eta(Y)\overset{\circ}{\nabla}_X \xi$$

for any differentiable vector fields X, Y over M . Then $\nabla'_X \xi = 0$.

Next, let us define $\bar{\nabla}$ by

$$\bar{\nabla}_X Y = \nabla'_X Y + ((\nabla'_X \eta)Y)\xi$$

Then, $\bar{\nabla}_X \xi = 0$ and $(\bar{\nabla}_X \eta)Y = 0$.

Finally, define

$$\nabla_X Y = \bar{\nabla}_X Y - \frac{1}{2}\varphi(\bar{\nabla}_X \varphi)Y.$$

This connection ∇ satisfies the required conditions.

We call such an affine connection a (φ, ξ, η) -connection. The following proposition is easily obtained.

Proposition 2.2. *Let $\overset{\circ}{\nabla}$ be an affine connection on M such that $\overset{\circ}{\nabla}\xi = \overset{\circ}{\nabla}\eta = 0$. Then, an affine connection ∇ on M such that $\nabla\xi = \nabla\eta = 0$, is always of the form $\nabla = \overset{\circ}{\nabla} + Q$ where Q is a tensor field of type $(1, 2)$ verifying*

$$(1) \quad Q(X, \xi) = 0 \qquad (2) \quad \eta(Q(X, Y)) = 0$$

for any vector fields X, Y on M .

Now, let ∇ be an affine connection such that $\nabla\xi = \nabla\eta = 0$. If $\nabla\varphi = 0$, then

$$(2.6) \quad 0 = \varphi(\overset{\circ}{\nabla}_X \varphi) Y + \varphi(Q(X, \varphi Y)) - \varphi^2 Q(X, Y)$$

being Q a tensor field of type (1,2) in the conditions of Proposition 2.1. If we put

$$P(X, Y) = -\frac{1}{2} \varphi(\overset{\circ}{\nabla}_X \varphi) Y$$

then, (2.6) is written as follows

$$(2.7) \quad P(X, Y) = F_2 Q(X, Y);$$

but, $P(X, Y) = -\varphi^2 P(X, Y)$, and then, by (2.5),

$$F_1 P(X, Y) = -\frac{1}{2} \varphi^2 P(X, \eta(Y)\xi) = 0$$

and, by (2.4),

$$F_2 P(X, Y) = -\varphi^2 P(X, Y) = P(X, Y).$$

Hence, (2.7) is written as follows

$$F_2(Q(X, Y) - P(X, Y)) = 0 = -\frac{1}{2} \varphi^2(Q(X, \eta(Y)\xi) - P(X, \eta(Y)\xi)).$$

Then, from (2.5), there exists a tensor field A such that

$$F_1 A(X, Y) = -\varphi^2(Q(X, Y) - P(X, Y)) = Q(X, Y) - P(X, Y).$$

Therefore Q must be of the form

$$Q(X, Y) = P(X, Y) + F_1(A(X, Y))$$

and $Q(X, \xi) = 0$, i.e. $\varphi A(X, \xi) = 0$.

Conversely, if $\overset{\circ}{\nabla}$ is an affine connection on M such that $\overset{\circ}{\nabla}\xi = \overset{\circ}{\nabla}\eta = 0$, and if A is a tensor field of type (1, 2) satisfying $\varphi A(X, \xi) = 0$, then the connection ∇ defined by

$$\nabla_X Y = \overset{\circ}{\nabla}_X Y - \frac{1}{2} \varphi(\overset{\circ}{\nabla}_X \varphi) Y + F_1 A(X, Y)$$

is a (φ, ξ, η) -connection. Thus, we have

Theorem 2.2. *Let $\overset{\circ}{\nabla}$ be an affine connection on M such that $\overset{\circ}{\nabla}\xi = \overset{\circ}{\nabla}\eta = 0$. Then, every (φ, ξ, η) -connection on M is of the form*

$$\nabla_X Y = \overset{\circ}{\nabla}_X Y - \frac{1}{2}\varphi(\overset{\circ}{\nabla}_X \varphi)Y + F_1 A(X, Y)$$

being A a tensor field of type $(1, 2)$ such that $\varphi A(X, \xi) = 0$ for any vector fields X, Y on M .

Corollary 2.1. *Let ∇ be a (φ, ξ, η) -connection on M . Then, a connection $\widetilde{\nabla}$ of the form*

$$\widetilde{\nabla}_X Y = \nabla_X Y + H(X, Y)$$

being H a tensor field of type $(1, 2)$, is a (φ, ξ, η) -connection, if and only if $H(X, \xi) = 0$ and $H(X, Y) = F_1 B(X, Y)$ for some tensor field B of type $(1, 2)$.

Proof. Let $\overset{\circ}{\nabla}$ be a (φ, ξ, η) -connection. Then,

$$\widetilde{\nabla}_X Y = \overset{\circ}{\nabla}_X Y - \frac{1}{2}\varphi(\overset{\circ}{\nabla}_X \varphi)Y + F_1 A(X, Y)$$

with $\varphi A(X, \xi) = 0$. On the other hand

$$\nabla_X Y + H(X, Y) = \overset{\circ}{\nabla}_X Y - \frac{1}{2}\varphi(\overset{\circ}{\nabla}_X \varphi)Y + F_1 A'(X, Y) + H(X, Y)$$

with $F_1 A'(X, \xi) = 0$. Therefore,

$$H(X, Y) = F_1(A(X, Y) - A'(X, Y)) = F_1 B(X, Y)$$

being $B = A - A'$ and $H(X, \xi) = F_1(A(X, \xi) - A'(X, \xi)) = 0$. Now, if

$$\widetilde{\nabla}_X Y = \nabla_X Y + H(X, Y)$$

with $H(X, \xi) = 0$ and $H(X, Y) = F_1 B(X, Y)$, then

$$\widetilde{\nabla}_X Y = \overset{\circ}{\nabla}_X Y - \frac{1}{2}\varphi(\overset{\circ}{\nabla}_X \varphi)Y + F_1(A(X, Y) + B(X, Y))$$

$$F_1(A(X, \xi) + B(X, \xi)) = 0$$

hence $\widetilde{\nabla}$ is a (φ, ξ, η) -connection.

Theorem 2.3. *Let (φ, ξ, η) be an almost contact structure on M . Then, there exists a symmetric (φ, ξ, η) -connection if and only if $N_\varphi = 0$ and $d\eta = 0$, being N_φ the Nijenhuis tensor of φ*

$$N_\varphi(X, Y) = -\varphi^2[X, Y] + \varphi[\varphi X, Y] + \varphi[X, \varphi Y] - [\varphi X, \varphi Y].$$

Proof. If ∇ is a symmetric (φ, ξ, η) -connection, then it follows immediately that $N_\varphi = 0$ and $d\eta = 0$.

Conversely, assume that $N_\varphi = 0$ and $d\eta = 0$. Then we define a symmetric (φ, ξ, η) -connection as follows.

Let $\overset{\circ}{\nabla}$ be an affine connection such that $\overset{\circ}{\nabla}\xi = \overset{\circ}{\nabla}\eta = 0$, and such that its torsion tensor is given [3] by $T(X, Y) = 2d\eta \otimes \xi$.

Then, ∇ given by

$$\nabla_X Y = \overset{\circ}{\nabla}_X Y - \frac{1}{2}\varphi(\overset{\circ}{\nabla}_X \varphi)Y$$

is a (φ, ξ, η) -connection, and the torsion tensor S of ∇ is given by

$$S(X, Y) = T(X, Y) - \frac{1}{2}(\varphi(\overset{\circ}{\nabla}_X \varphi)Y - \varphi(\overset{\circ}{\nabla}_Y \varphi)X).$$

But $d\eta = 0$ implies $T = 0$, and therefore

$$\begin{aligned} S(X, \xi) &= -\frac{1}{2}(\varphi(\overset{\circ}{\nabla}_X \varphi)\xi - \varphi(\overset{\circ}{\nabla}_\xi \varphi)X) = \frac{1}{2}\varphi(\overset{\circ}{\nabla}_\xi \varphi X - \varphi \overset{\circ}{\nabla}_\xi X) \\ &= \frac{1}{2}\varphi(-[\varphi X, \xi] + \varphi[X, \xi]) = \frac{1}{2}(\varphi^2[X, \xi] - \varphi[\varphi X, \xi]) = -\frac{1}{2}N_\varphi(X, \xi) = 0. \end{aligned}$$

Hence, by Corollary (2.1), the connection $\bar{\nabla}$ given by

$$\bar{\nabla}_X Y = \nabla_X Y - F_1 F_4 S(X, Y)$$

is a (φ, ξ, η) -connection, being F_4 the linear operator over the space of tensors of type (1, 2) defined by

$$F_4 P(X, Y) = \frac{1}{2}\{-\varphi^2 P(X, Y) + P(\varphi X, \varphi Y)\}.$$

Denoting by \bar{T} the torsion tensor of $\bar{\nabla}$ we obtain

$$\bar{T}(X, Y) = S(X, Y) - F_1 F_4 S(X, Y) + F_1 F_4 S(Y, X)$$

$$\begin{aligned}
&= S(X, Y) - \frac{1}{4}\{\varphi^4 S(X, Y) + \varphi^3 S(X, \varphi Y) - \varphi^2 S(\varphi X, \varphi Y) \\
&- \varphi S(\varphi X, \varphi^2 Y)\} + \frac{1}{4}\{\varphi^4 S(Y, X) + \varphi^3 S(Y, \varphi X) - \varphi^2 S(\varphi Y, \varphi X) - \varphi S(\varphi Y, \varphi^2 X)\} \\
&= S(X, Y) - \frac{1}{4}\{S(X, Y) + \varphi S(X, \varphi Y) + S(\varphi X, \varphi Y) \\
&+ \varphi S(\varphi X, Y)\} + \frac{1}{4}\{S(Y, X) + \varphi S(Y, \varphi X) + S(\varphi Y, \varphi X) + \varphi S(\varphi Y, X)\} \\
&= \frac{1}{2}S(X, Y) - \frac{1}{2}S(\varphi X, \varphi Y).
\end{aligned}$$

If now we define

$$F_3 P(X, Y) = \frac{1}{2}\{-\varphi^2 P(X, Y) - P(\varphi X, \varphi Y)\}$$

then

$$\bar{T}(X, Y) = F_3 S(X, Y).$$

But

$$\begin{aligned}
F_3 S(X, Y) &= \frac{1}{2}F_3(\varphi(\overset{\circ}{\nabla}_X \varphi) Y - \varphi(\overset{\circ}{\nabla}_Y \varphi) X) \\
&= -\frac{1}{4}\{-\varphi^3(\overset{\circ}{\nabla}_X \varphi) Y - \varphi(\overset{\circ}{\nabla}_{\varphi X} \varphi) \varphi Y - (-\varphi^3(\overset{\circ}{\nabla}_Y \varphi) X - \varphi(\overset{\circ}{\nabla}_{\varphi Y} \varphi) X)\} \\
&= -\frac{1}{4}\{\varphi(\overset{\circ}{\nabla}_X \varphi) Y - (\overset{\circ}{\nabla}_{\varphi X} \varphi) \varphi Y - \varphi(\overset{\circ}{\nabla}_Y \varphi) X + (\overset{\circ}{\nabla}_{\varphi Y} \varphi) X\} \\
&= -\frac{1}{4}N\varphi(X, Y) = 0
\end{aligned}$$

and the proof is complete.

3 - Affine connections on manifolds with an almost contact 3-structure

Lemma 3.1. *On a differentiable manifold M , with an almost contact 3-structure $(\varphi_i, \xi_i, \eta^i)$ ($i = 1, 2, 3$) there always exists an affine connection such that φ_i, ξ_i, η^i are covariantly constant with respect to it.*

We call such an affine connection a $(\varphi_i, \xi_i, \eta^i)$ -connection.

Proof. Given a lineal connection $\hat{\nabla}$, define

$$\nabla'_X Y = \hat{\nabla}_X Y - \sum_{i=1}^3 \eta^i(Y) \hat{\nabla}_X \xi_i.$$

Then, $\nabla'_X \xi_i = 0$ ($i = 1, 2, 3$). Now

$$\bar{\nabla}_X Y = \nabla'_X Y + \sum_{i=1}^3 ((\nabla'_X \eta^i) Y) \xi_i$$

satisfies $\bar{\nabla}_X \xi = \bar{\nabla}_X \eta^i = 0$ ($i = 1, 2, 3$). Finally

$$\nabla_X Y = \bar{\nabla}_X Y - \frac{1}{4} \sum_{i=1}^3 \varphi_i (\bar{\nabla}_X \varphi_i) Y$$

is a $(\varphi_i, \xi_i, \eta^i)$ -connection.

By using the almost contact 3-structure $(\varphi_i, \xi_i, \eta^i)$ ($i = 1, 2, 3$) we define linear operators $F_1, F_2, F_3, F_4, G_1, G_2, G_3, G_4, H_1, H_2, H_3, H_4$, respectively, in the same way as we did in 2.

The following proposition is easily proved.

Proposition 3.1. *Let ∇ be a $(\varphi_i, \xi_i, \eta^i)$ -connection. Let be*

$$\hat{\nabla}_X Y = \nabla_X Y + H(X, Y)$$

being H a tensor field of type (1, 2). Then $\hat{\nabla}$ is a $(\varphi_i, \xi_i, \eta^i)$ -connection if and only if

$$F_2 H(X, Y) = G_2 H(X, Y) \quad H(X, \xi_i) = 0 \quad \eta^i(H(X, Y)) = 0 \quad (i = 1, 2, 3)$$

for any vector fields X, Y on M .

Proposition 3.2. *Let H be a tensor field of type (1, 2). Then $\eta^i(H(X, Y)) = 0, H(X, \xi_i) = 0$ and $F_2 H = G_2 H = 0$ if and only if there exists a tensor field Q of type (1, 2) such that*

$$H(X, Y) = F_1 G_1 Q(X, Y) \quad Q(X, \xi_i) = 0 \quad \eta^i(Q(X, Y)) = 0.$$

Proof. If $F_2H(X, Y) = 0$ and $H(X, \xi_i) = 0$, then, by (2.4), $F_1H(X, Y) = H(X, Y)$.

If $G_2H(X, Y) = 0$, then, $G_1H(X, Y) = H(X, Y)$. Therefore $F_1G_1H(X, Y) = F_1H(X, Y) = H(X, Y)$ and it is sufficient to take $Q = H$.

Conversely, if there exists a tensor field Q satisfying $H(X, Y) = F_1G_1Q(X, Y)$, $Q(X, \xi_i) = 0$ and $\eta^i(Q(X, Y)) = 0$, then, $H(X, \xi_i) = 0$ and $\eta^i(H(X, Y)) = 0$.

Finally, from (2.5), $H(X, Y) = F_1G_1Q(X, Y) = G_1F_1Q(X, Y)$ imply $F_2H(X, Y) = 0$, $G_2H(X, Y) = 0$.

Using Propositions 3.1 and 3.2 we can state

Theorem 3.1. *Let ∇ be a $(\varphi_i, \xi_i, \eta^i)$ -connection. Then*

$$\tilde{\nabla}_X Y = \nabla_X Y + H(X, Y)$$

is a $(\varphi_i, \xi_i, \eta^i)$ -connection if and only if there exists a tensor field Q of type (1, 2) such that

$$Q(X, \xi_i) = 0 \quad \eta^i(Q(X, Y)) = 0 \quad H(X, Y) = F_1G_1Q(X, Y)$$

for any vector fields X, Y on M .

The next proposition is easily obtained.

Proposition 3.3. *Let P be a tensor field of type (1, 2) such that $P(X, \xi) = \eta^i(P(X, Y)) = 0$. Then*

$$\begin{aligned} F_1G_1P(X, Y) &= G_1H_1P(X, Y) = H_1F_1P(X, Y) \\ &= G_1F_1P(X, Y) = H_1G_1P(X, Y) = F_1H_1P(X, Y) \\ &= \frac{1}{4} \{P(X, Y) - \varphi_1P(X, \varphi_1Y) - \varphi_2P(X, \varphi_2Y) - \varphi_3P(X, \varphi_3Y)\} \end{aligned}$$

hold good for any vector fields X, Y on M .

Theorem 3.2. *Let $(\varphi_i, \xi_i, \eta^i)$ ($i = 1, 2, 3$) be an almost contact 3-structure on M . Then, there exists a symmetric $(\varphi_i, \xi_i, \eta^i)$ -connection if and only if $N_{\varphi_i} = 0$, $d\eta^i = 0$ and $\mathfrak{L}_{\xi_i}\varphi_i = 0$, where \mathfrak{L} denotes the Lie differentiation.*

Proof. If ∇ is a symmetric $(\varphi_i, \xi_i, \eta^i)$ -connection, then the conditions $N_{\varphi_i} = 0$, $d\eta^i = 0$, and $\mathcal{L}_{\xi_i} \varphi_i = 0$ follow immediately. Now, suppose

$$N_{\varphi_i} = 0 \quad d\eta^i = 0 \quad \mathcal{L}_{\xi_i} \varphi_i = 0.$$

Let $\overset{\circ}{\nabla}$ be an affine connection such that $\overset{\circ}{\nabla} \xi_i = 0$, $\overset{\circ}{\nabla} \eta^i = 0$, and with torsion tensor [6]

$$\overset{\circ}{T} = \sum_{i=1}^3 d\eta^i \otimes \xi_i.$$

Then $d\eta^i = 0$ implies $\overset{\circ}{T} = 0$. Define

$$\nabla_X Y = \overset{\circ}{\nabla}_X Y - \frac{1}{4} \sum_{i=1}^3 \varphi_i(\overset{\circ}{\nabla}_X \varphi_i) Y.$$

Then, ∇ is a $(\varphi_i, \xi_i, \eta^i)$ -connection and its torsion tensor is given by

$$S(X, Y) = -\frac{1}{4} \left\{ \sum_{i=1}^3 \varphi_i(\overset{\circ}{\nabla}_X \varphi_i) Y - \sum_{i=1}^3 \varphi_i(\overset{\circ}{\nabla}_Y \varphi_i) X \right\}.$$

A straightforward computation shows that $S(X, \xi_i) = 0$ and $\eta^i S(X, Y) = 0$; therefore, from Theorem 2.1, if

$$\nabla'_X Y = \nabla_X Y - 4G_1 F_1 F_4 S(X, Y)$$

then ∇' is a $(\varphi_i, \xi_i, \eta^i)$ -connection. But the torsion tensor of ∇' is given by $S'(X, Y) = F_3(N_{\varphi_2} + N_{\varphi_3})$ and, therefore, ∇' is symmetric.

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Summary

See Introduction.
