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Regularity results for some degenerate parabolic equation ()****1 - Introduction**

Let $d \in \mathbb{N}$ and set $H = \mathbb{R}^d$. We denote by $|\cdot|$ the norm, and by $\langle \cdot, \cdot \rangle$ the inner product in H . By $L(H)$ we mean the algebra of all linear operators from H into itself, and by $L_+(H)$ the subset of $L(H)$ of all symmetric nonnegative linear operators.

Moreover for any function $\varphi: H \rightarrow \mathbb{R}$, $D\varphi$ is its gradient and D_i , $i = 1, \dots, d$, is its partial derivative with respect to x_i .

We are concerned with the parabolic equation

$$(1.1) \quad \begin{cases} D_t u(t, x) = Nu(t, \cdot)(x), & x \in H, t > 0, \\ u(0, x) = \varphi(x), & x \in H, \end{cases}$$

where N is the differential operator

$$(1.2) \quad N\varphi(x) = \frac{1}{2} \text{Tr}[CD^2\varphi(x)] + \langle Ax + F(x), D\varphi(x) \rangle, \quad x \in H.$$

We recall that a *strict* solution of (1.1) is a function $u: [0, +\infty) \times H \rightarrow H$, $(t, x) \rightarrow u(t, x)$ that is continuously differentiable with respect to t , twice continuously differentiable with respect to x and fulfills (1.1). We shall assume,

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(**) Received October 1, 1999. AMS classification 35 K 15, 34 K 65, 35 H 05.

Hypothesis 1.1. (i) $A \in L(H)$, $C \in L_+(H)$.

(ii) $F \in C_b^2(H; H)$ ⁽¹⁾.

The following result is well known, see e.g. [6], however we shall give a sketch of the proof for the reader's convenience.

Proposition 1.2. *Assume that Hypothesis 1.1 holds. Then for all $\varphi \in C_b^2(H)$, problem (1.1) has a unique strict solution u . u is given by the formula*

$$(1.3) \quad u(t, x) = \mathbb{E}[\varphi(X(t, x))], \quad t \geq 0, \quad x \in H,$$

where $X(\cdot, x)$ is the solution of the differential stochastic equation

$$(1.4) \quad \begin{cases} dX(t) = (AX(t) + F(X(t))) dt + C^{1/2} dW(t) \\ X(0) = x, \end{cases}$$

W is a standard Brownian motion in a probability space $(\Omega, \mathcal{F}, \mathbb{P})$ taking values on \mathbb{R}^d , and \mathbb{E} means expectation.

Proof. The differential stochastic equation (1.4) can be solved by a fixed point argument. Moreover, since $F \in C_b^2(H; H)$, $X(t, x)$ is twice differentiable in x , and the partial derivatives:

$$X_x(t, x) \cdot h = \eta^h(t, x), \quad t \geq 0, \quad x, h \in H,$$

and

$$X_{xx}(t, x)(h, h) = \zeta^h(t, x), \quad t \geq 0, \quad x, h \in H,$$

⁽¹⁾ If H and K are Hilbert spaces we denote by $C_b(H; K)$ (resp. $B_b(H; K)$) the Banach space of all uniformly continuous (resp. Borel) and bounded mappings from H into K , endowed with the sup norm $\|\cdot\|_0$. Moreover, for any $k \in \mathbb{N}$, $C_b^k(H; K)$ will represent the Banach space of all mappings from H into K , that are uniformly continuous and bounded together with their Fréchet derivatives of order less or equal to k endowed with their natural norm $\|\cdot\|_k$. Finally we set $C_b^\infty(H; K) = \bigcap_{k=1}^{\infty} C_b^k(H; K)$. If $K = \mathbb{R}$ we set $C_b(H; K) = C_b(H)$ (resp. $B_b(H; K) = B_b(H)$) and $C_b^k(H; K) = C_b^k(H)$, $C_b^\infty(H) = C_b^\infty(H; K)$.

are the solutions to the following differential stochastic equations

$$(1.5) \quad \begin{cases} \frac{d}{dt} \eta^h(t, x) = (A + DF(X(t, x))) \eta^h(t, x) \\ \eta^h(0, x) = h, \end{cases}$$

and

$$(1.6) \quad \begin{cases} \frac{d}{dt} \zeta^h(t, x) = (A + DF(X(t, x))) \zeta^h(t, x) + D^2F(X(t, x))(\eta^h(t, x), \eta^h(t, x)) \\ \zeta^h(0, x) = 0, \end{cases}$$

respectively, see e.g. [6]. From (1.5) and the Gronwall lemma, it follows

$$(1.7) \quad |\eta^h(t, x)| \leq e^{(\|A\| + \|F\|_1)t} |h|, \quad x, h \in H.$$

Therefore, from (1.6) we find

$$(1.8) \quad \begin{aligned} |\zeta^h(t, x)| &\leq \int_0^t e^{(t-s)(\|A\| + \|F\|_1)} |D^2F(\eta^h(s, x), \eta^h(s, x))| ds \\ &\leq \int_0^t e^{(t-s)(\|A\| + \|F\|_1)} \|F\|_2 e^{s(\|A\| + \|F\|_1)} ds \\ &= \|F\|_2 \int_0^t e^{(t+s)(\|A\| + \|F\|_1)} ds. \end{aligned}$$

It follows that $u(t, \cdot) \in C_b^2(H)$ and

$$(1.9) \quad \langle Du(t, x), h \rangle = \mathbb{E}[\langle D\varphi(X(t, x)), X_x(t, x) h \rangle], \quad t \geq 0, \quad x, h \in H,$$

and

$$(1.10) \quad \begin{aligned} \langle D^2u(t, x) h, h \rangle &= \mathbb{E}[\langle D^2\varphi(X(t, x)) X_x(t, x) h, X_x(t, x) h \rangle] \\ &\quad + \mathbb{E}[\langle D\varphi(X(t, x)), X_{xx}(t, x)(h, h) \rangle] \quad t \geq 0, \quad x, h \in H. \end{aligned}$$

Now the conclusion follows from the Itô formula. ■

Remark 1.3. In a similar way we can show that if $F \in C_b^k(H; H)$ for some $k > 3$ and $\varphi \in C_b^k(H)$ then $u(t, \cdot) \in C_b^k(H)$ for any $t \geq 0$.

We note that Proposition 1.2 has been proved by deterministic methods in [8] when $\det C > 0$ and in [7] when $F = 0$.

We define now a semigroup of linear bounded operators in $B_b(H)$ by setting

$$(1.11) \quad P_t \varphi(x) = \mathbb{E}[\varphi(X(t, x))], \quad \varphi \in B_b(H), \quad t \geq 0,$$

this definition is meaningful since φ is bounded and Borel and X is continuous.

It is easy to see that P_t has the *Feller* property, that is the following implication holds:

$$(1.12) \quad \varphi \in C_b(H), t \geq 0 \Rightarrow P_t \varphi \in C_b(H).$$

Consequently the restriction of $P_t, t \geq 0$ to $C_b(H)$ is a semigroup of linear bounded operators in $C_b(H)$ (not strongly continuous in general, see [1] and [9]).

The goal of this paper is to find sufficient conditions such that $P_t \varphi$ is differentiable in x for all $t > 0$ and for all $\varphi \in C_b(H)$. We are also interested in the behaviour of the derivative $DP_t \varphi$ for t close to 0, arriving to estimates such as

$$(1.13) \quad |DP_t \varphi(x)| \leq ct^{-k/2} \|\varphi\|_0,$$

for some $k \in \mathbb{N}$.

We believe that it would be possible to find estimates, under suitable additional assumption, also for higher derivatives of φ . These estimates could be useful to prove Schauder estimates for the elliptic equation

$$(1.14) \quad \lambda \varphi - N\varphi = f,$$

see [7]. However we shall only prove (1.13) for $k = 1$. As a consequence we will find that the transition semigroup P_t enjoys the strong Feller property, that is:

$$(1.15) \quad \varphi \in B_b(H), t > 0 \Rightarrow P_t \varphi \in C_b(H).$$

Strong Feller property is important to study uniqueness of invariant measures, see [4].

When $F = 0$ there is a complete answer to the above problems that we recall in § 2. In § 3 we consider a perturbation of the linear case. Finally in § 4 we give an example.

2 - The case when $F = 0$

We assume here $F = 0$. Then P_t is given, as well known, by the following Mehler formula:

$$(2.1) \quad P_t \varphi(x) = \int_H \varphi(e^{tA}x + y) \mathfrak{N}(0, Q_t)(dy), \quad \varphi \in B_b(H),$$

where

$$(2.2) \quad Q_t = \int_0^t e^{sA} C e^{sA*} ds,$$

and $\mathfrak{N}(0, Q_t)$ is the gaussian measure having mean 0 and covariance operator Q_t .

The following result is also well known, see e.g. [3],

Proposition 2.1. *The following statements are equivalent:*

- (i) $\det Q_t > 0$, for all $t > 0$.
- (ii) For all $\varphi \in B_b(H)$ and for any $t > 0$ we have $P_t \varphi \in C_b^\infty(H)$. Moreover, if (i) holds we have

$$(2.3) \quad \|D^k P_t \varphi(x)\| \leq \|A(t)\|^k \|\varphi\|_0, \quad t > 0, \quad k \in \mathbb{N},$$

where

$$(2.4) \quad A(t) = Q_t^{-1/2} e^{tA}, \quad t > 0.$$

We recall that when $C = I$ and $\|e^{tA}\| \leq e^{\omega t}$, $t \geq 0$, we have

$$(2.5) \quad \|A(t)\| \leq \frac{e^{\omega t}}{t^{1/2}},$$

whereas if $\det C = 0$, but $\det Q_t > 0$, $t > 0$, there exists $k \in \{3, 5, \dots, 2d - 1\}$, and a positive constant c_k such that

$$(2.6) \quad \|A(t)\| \leq c_k \frac{e^{\omega t}}{t^{k/2}}.$$

We recall that assumption (i) of Proposition 2.1 is equivalent to the Hörmander condition, see [5], ensuring hypoellipticity of N , and also to the controllability of

the deterministic system

$$(2.7) \quad \xi' = A\xi + C^{1/2}\eta, \quad \xi(0) = \xi_0,$$

where ξ is the state and η the control. In fact, given $T > 0$ and $\xi_0 \in H$, the control

$$\eta(s) = -C^{1/2}e^{(T-s)A^*}Q_T^{-1}e^{TA}\xi_0, \quad s \in [0, T],$$

drives system (2.7) to 0 in time T .

3 - The case when $F \neq 0$

Let $\varphi \in C_b^2(H)$ and let u be the strict solution of (1.1). First we are going to prove an estimate for $Du(t, x)$ depending on $\|\varphi\|_0$ but not on $\|D\varphi\|_0$. To do this, we shall use a generalization of a well known method due to Bernstein.

We set

$$(3.1) \quad z(t, x) = u^2(t, x) + \langle G(t) Du(t, x), Du(t, x) \rangle, \quad x \in H, \quad t \geq 0,$$

where $G(t)$, $t \geq 0$ are symmetric positive matrices, to be specified later, whose matrix elements will be denoted by $(G_{i,j}(t))$.

We will need the following identities involving the differential operator N , that can be easily checked.

$$(3.2) \quad N(\varphi\psi) = \varphi N\psi + \psi N\varphi + \langle CD\varphi, D\psi \rangle, \quad \varphi, \psi \in C_b^2(H),$$

and

$$(3.3) \quad D_i N\varphi = ND_i\varphi + \langle D_i F(x), D\varphi \rangle, \quad \varphi, \psi \in C_b^2(H), \quad i = 1, 2, \dots, d.$$

Lemma 3.1. *Let $\varphi \in C_b^3(H)$, $u(t, \cdot) = P_t\varphi$, and let $G \in C^1([0, +\infty)); L(H)$ with $G(t)$ symmetric for all $t \geq 0$. Then the following identity holds:*

$$(3.4) \quad \begin{aligned} D_t z(t, x) &= Nz(t, \cdot)(x) + \langle G'(t) Du(t, x), Du(t, x) \rangle \\ &+ 2\langle (A + DF(x)) G(t) Du(t, x), Du(t, x) \rangle - \langle CDu(t, x), Du(t, x) \rangle \\ &- \text{Tr}[CD^2u(t, x) G(t) D^2u(t, x)]. \end{aligned}$$

Proof. We first notice that by (3.2) we have

$$(3.5) \quad D_t(u^2) = 2u D_t u = 2uNu = N(u^2) - |C^{1/2}Du|^2.$$

Let us compute $D_t(D_i u D_j u)$. Taking into account (3.3) we have

$$\begin{aligned} D_t(D_i u D_j u) &= D_i N u D_j u + D_i u D_j N u \\ &= N D_i u D_j u + N D_j u D_i u + \langle D_i F, Du \rangle D_j u + \langle D_j F, Du \rangle D_i u . \end{aligned}$$

By (3.2) it follows

$$\begin{aligned} D_t(D_i u D_j u) &= N(D_i u D_j u) - \langle C D D_i u, D D_j u \rangle \\ &\quad + \langle D_i F, Du \rangle D_j u + \langle D_j F, Du \rangle D_i u . \end{aligned}$$

Let us compute $D_t(\langle G(t) Du, Du \rangle)$,

$$\begin{aligned} (3.6) \quad D_t(\langle G(t) Du, Du \rangle) &= D_t(\langle G'(t) Du, Du \rangle) + \sum_{i,j=1}^d G_{i,j}(t) D_t(D_i u D_j u) \\ &= D_t(\langle G'(t) Du, Du \rangle) + \sum_{i,j=1}^d N((D_i u D_j u)) - \sum_{i,j=1}^d G_{i,j}(t) \langle C D D_i u, D D_j u \rangle \\ &\quad + 2 \sum_{i,j=1}^d G_{i,j}(t) \langle D_i F, Du \rangle D_j u . \end{aligned}$$

From (3.5) and (3.6) the conclusion follows. ■

We prove now the main result of the paper. In its formulation we set

$$(3.7) \quad G(t) = [A(t)^* A(t)]^{-1} = \int_0^t e^{-sA} C e^{-sA^*} ds, \quad t \geq 0 .$$

Moreover we recall that $P_t \varphi$ is defined by (1.11).

Theorem 3.2. *Assume, besides Hypothesis 1.1, that $\det Q_t > 0$ for $t > 0$, and*

$$(3.8) \quad \langle DF(x) G(t) \xi, \xi \rangle \leq \kappa \langle G(t) \xi, \xi \rangle, \quad t > 0, \quad \xi \in H ,$$

for some $\kappa \in \mathbb{R}$.

Then for any $\varphi \in C_b(H)$ and any $t > 0$ we have $P_t \varphi \in C_b^1(H)$. Moreover the following estimate holds

$$(3.9) \quad |DP_t \varphi(x)| \leq e^{\kappa t/2} \|A(t)\| \|\varphi\|_0, \quad t > 0, \quad x \in H .$$

Finally if $\varphi \in B_b(H)$, and $t > 0$, then $P_t \varphi$ is Lipschitz continuous, so that P_t is strong Feller.

Proof. We first prove the assertion for $\varphi \in C_b^3(H)$. For this purpose we use Lemma 3.1 taking

$$G(t) = [A(t)^* A(t)]^{-1} = \int_0^t e^{-sA} C e^{-sA^*} ds .$$

By a straightforward computation we find

$$G'(t) + AG(t) + G(t) A^* - C = 0, \quad t \geq 0,$$

so that, taking into account that

$$\text{Tr}[CD^2 u(t, x) G(t) Du^2(t, x)] > 0,$$

(3.4) yields the following

$$\begin{aligned} D_t z(t, x) &= Nz(t, \cdot)(x) + \langle DF(x) G(t) Du(t, x), Du(t, x) \rangle \\ &\quad - \text{Tr}[CD^2 u(t, x) G(t) D^2 u(t, x)] \\ &\leq Nz(t, \cdot)(x) + \kappa \langle G(t) Du(t, x), Du(t, x) \rangle. \end{aligned}$$

Therefore

$$\begin{aligned} &\langle G(t) Du(t, x), Du(t, x) \rangle \leq z(t, x) \\ &\leq P_t(\varphi^2(x)) + \kappa \int_0^t P_{t-s}(\langle G(s) Du(s, \cdot), Du(s, \cdot) \rangle)(x) ds, \end{aligned}$$

and consequently

$$\begin{aligned} &\sup_{x \in H} \langle G(t) Du(t, x), Du(t, x) \rangle \\ &\leq \|\varphi\|_0^2 + \kappa \int_0^t \sup_{x \in H} \langle G(s) Du(s, x), Du(s, x) \rangle ds. \end{aligned}$$

By the Gronwall lemma it follows

$$\langle G(t) Du(t, x), Du(t, x) \rangle \leq e^{\kappa t} P_t(\varphi^2), \quad t \geq 0.$$

Finally we have

$$|Du(t, x)|^2 \leq \|A(t)\|^2 \langle G(t) Du(t, x), Du(t, x) \rangle \leq e^{\kappa t} \|\varphi\|_0^2,$$

and (3.9) is proved when $\varphi \in C_b^2(H)$.

Let now $\varphi \in C_b(H)$, and let $\{\varphi_n\} \subset C_b^3(H)$ such that $\varphi_n \rightarrow \varphi$ in $C_b(H)$. Set

$$u_n(t, x) = P_t \varphi_n(x), \quad x \in H, \quad t \geq 0.$$

Then by (3.9) it follows that, for any $m, n \in \mathbb{N}$,

$$|Du_n(t, x) - Du_m(t, x)| \leq e^{\kappa t/2} \|A(t)\| \|\varphi_n - \varphi_m\|_0.$$

This implies that $u(t, \cdot) \in C_b^1(H)$ and (3.9) holds.

Let finally $t > 0$ be fixed and $\varphi \in B_b(H)$. Let $\{\varphi_n\} \subset C_b^1(H)$ such that $\varphi_n(x) \rightarrow \varphi(x)$ almost everywhere and $\|\varphi_n\|_0 \leq \|\varphi\|_0$. Then for any $n \in \mathbb{N}$, we have, by the first part of the proof,

$$|u_n(t, x) - u_n(t, y)| \leq e^{\kappa_1 t/2} \|A(t)\| \|\varphi\|_0 |x - y|,$$

for all $x, y \in H$. Consequently, by the Ascoli–Arzelà lemma, there exists a subsequence $\{u_{n_k}\}$ such that

$$\lim_{k \rightarrow \infty} u_{n_k}(t, x) \rightarrow u(t, x), \quad \text{uniformly on the compact subsets of } H,$$

where $u(t, x) = P_t \varphi(x)$. Therefore $P_t \varphi$ is continuous as required. ■

3.1 - A generalization

We assume here that Hypothesis 1.1–(i) holds, but we replace Hypothesis 1.1–(ii) by the following

Hypothesis 3.3. *F is locally Lipschitz continuous, and there exists $\eta \in \mathbb{R}$ such that*

$$(3.10) \quad \langle F(x) - F(y), x - y \rangle \leq \eta |x - y|^2, \quad x, y \in H.$$

Under these assumptions the differential stochastic equation (1.4) can be solved by monotonicity methods, see [6] and [3], Chapter 5. Then we can still define the transition semigroup

$$u(t, x) = P_t \varphi(x) = \mathbb{E}[\varphi(X(t, x))], \quad t \geq 0, \quad x \in H,$$

for all $\varphi \in B_b(H)$. However if $\varphi \in C_b^2(H)$, we cannot conclude that u is a strict solution to (1.1). In fact we do not know whether $X(t, x)$ is twice differentiable, and so we cannot use formulas (1.9) and (1.10). We shall say that u is a *generalized* solution of (1.1).

We prove finally the following result.

Theorem 3.4. *Assume, besides Hypotheses 1.1–(i) and Hypotheses 3.3, that $\det Q_t > 0$ for $t > 0$, and that (3.8) holds.*

Then for any $\varphi \in C_b(H)$ and any $t > 0$ we have $P_t \varphi \in C_b^1(H)$. Moreover the following estimate holds

$$(3.11) \quad |DP_t \varphi(x)| \leq e^{\kappa t/2} \|A(t)\| \|\varphi\|_0, \quad t > 0, \quad x \in H.$$

Finally if $\varphi \in B_b(H)$, and $t > 0$, then $P_t \varphi$ is Lipschitz continuous, so that P_t is strong Feller.

Proof. There exists a sequence $\{F_n\}$ in $C_b^2(H; H)$ such that

(i) We have

$$\lim_{n \rightarrow \infty} F_n(x) = F(x), \quad x \in H, \quad n \in \mathbb{N},$$

uniformly on the bounded subset of H .

(ii) We have

$$(3.12) \quad \langle F_n(x) - F_n(y), x - y \rangle \leq \eta |x - y|^2, \quad x, y \in H.$$

It is enough to set

$$F_n(x) = \int_H e^{-\frac{1}{2n}} F(e^{-\frac{1}{2n}} x + y) \mathcal{N}(0, (1 - e^{-\frac{1}{2n}}))(dy).$$

Let $X_n(t, x)$ be the solution to the differential stochastic equation

$$(3.13) \quad \begin{cases} dX_n(t) = (AX_n(t) + F_n(X_n(t))) dt + C^{1/2} dW(t) \\ X_n(0) = x, \end{cases}$$

and let P_t^n be the corresponding transition semigroup:

$$(3.14) \quad P_t^n \varphi(x) = \mathbb{E}[\varphi(X(t, x))], \quad \varphi \in B_b(H), \quad t \geq 0, \quad x \in H.$$

It is not difficult to see that $P_t^n \varphi(x) \rightarrow P_t \varphi(x)$ when $n \rightarrow \infty$ uniformly on the

bounded subsets of H , see e.g. [2], Chapter 2. Now by Theorem 3.4 we have the estimate

$$(3.15) \quad |DP_t^N \varphi(x)| \leq e^{\kappa t/2} \|A(t)\| \|\varphi\|_0, \quad t > 0, \quad x \in H, \quad N \in \mathbb{N},$$

for any $\varphi \in B_b(H)$. Now the conclusion follows from standard arguments. ■

4 - An example

We consider here the evolution equation in \mathbb{R}^2 ,

$$(4.1) \quad \begin{cases} D_t u(t, x) = \frac{1}{2} D_1^2 u(t, x) + x_1 D_2 u(t, x) + F_1(x) D_1 u(t, x) \\ \quad + F_2(x) D_2 u(t, x), \\ u(0, x) = \varphi(x), \quad x \in H. \end{cases}$$

It is a perturbation of a well known Kolmogorov equation.

In this case we have

$$A = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, \quad C = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix},$$

and

$$G(t) = \frac{t}{6} \begin{pmatrix} 6 & 2 - 3t \\ -3t & 2t^2 \end{pmatrix}.$$

It is easy to see that $\det Q_t > 0$ and

$$(4.2) \quad \|A(t)\| \leq ct^{-3/2}, \quad t \geq 0.$$

Lemma 4.1. *Let $M = \begin{pmatrix} -a & b \\ c & -d \end{pmatrix}$. Then $MG(t) \leq 0$ for any $t \geq 0$ if and only if*

$$b = c = 0, \quad a \geq 0, \quad d \geq 0,$$

and

$$\frac{d}{3} \leq a \leq 3d.$$

Corollary 4.2. Let $M = \begin{pmatrix} -a & 0 \\ 0 & -d \end{pmatrix}$, with $a \geq 0$, $d \geq 0$. Then we have

$$MG(t) \leq \kappa_1 G(t), \quad t \geq 0,$$

where

$$\kappa_1 = \sup \left\{ \frac{d - 3a}{2}, \quad \frac{a - 3d}{2} \right\}.$$

Now by Theorem 3.2 it follows the result

Proposition 4.3. Assume that $F_1(x) = f_1(x_1)$, $F_2(x) = f_2(x_2)$, with $f_1, f_2 \in C_b^2(\mathbb{R})$, $f_1 \leq 0$, $f_2 \leq 0$, and that there exists $c_1 > 0$ such that

$$|D_1 f_1(x_1)| + |D_2 f_1(x_2)| \leq c_1.$$

Then for any $\varphi \in C_b(H)$ and any $t > 0$ we have $P_t \varphi \in C_b^1(H)$. Moreover the following estimate holds

$$(4.3) \quad |DP_t \varphi(x)| \leq c e^{c_1 t/2} t^{-3/2} \|\varphi\|_0, \quad t > 0, \quad x \in H.$$

Acknowledgements. We thank the referee for a careful reading of the paper and for useful suggestions.

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Abstract

We consider a degenerate parabolic equation fulfilling controllability conditions and prove differentiability of the solution.
